

Chaptu 2: Itô calculus

①

In the absence of external potential, the simplest dynamics of an overdamped colloid is given by

$$\dot{x}(t) = \sqrt{\Gamma} \gamma(t) \quad (1)$$

where $\gamma(t)$ is a Gaussian white noise satisfying $\langle \gamma(t) \rangle = 0$

$$\langle \gamma(t) \gamma(t') \rangle = \delta(t-t')$$

Two problems

① $\frac{x(t+\tau) - x(t)}{\tau} \sim \sqrt{\frac{\Gamma}{\tau}} \xrightarrow[\tau \rightarrow 0]{} \infty \Rightarrow x(t) \text{ not differentiable}$

② Chain rule + causality problem $\langle x^2(t) \rangle = C^{\text{st}}$
which is wrong

Itô-calculus

$$\dot{x} = F(x) + \gamma(t) \Leftrightarrow dx(t) = F(x(t))dt + d\gamma \quad \begin{matrix} x(t+\delta t) - x(t) \\ \sim \\ x(t) \text{ for causality} \end{matrix}$$

① $\dot{x}(t)$ is just a notation, only $\int_0^t ds \dot{x}(s)$ makes sense

② Save causality & modify the chain rule:

$$\frac{d}{dt} [f(x(t))] = f'(x(t)) \dot{x}(t) + \frac{\Gamma}{2} f''(x(t)) \quad (2)$$

Stratonovich: $\dot{x} = F(x) + \gamma(t) \Leftrightarrow dx = F\left(x_t + \frac{dx}{2}\right)dt + d\gamma$ $\frac{1}{2}[x(t+\delta t) + x(t)] \Rightarrow \text{breaks causality}$

$$(2) \Leftrightarrow df(x(t)) = f'(x(t)) dx + \frac{\Gamma}{2} f''(x(t)) dt$$

not symmetrized \Rightarrow not a Stratonovich prescription

$$f'(x(t)) = f'\left(x(t) + \frac{dx}{2} - \frac{dx}{2}\right) = f'\left(x(t) + \underbrace{\frac{dx}{2}}_{\text{symmetric}}\right) - \frac{dx}{2} f''(x(t)) + O(dx^2) \quad (2)$$

$$f'(x(t)) dx = f'\left(x(t) + \frac{dx}{2}\right) dx - \frac{1}{2} f''(x(t)) dx^2$$

but to order dt , $dx^2 = d\gamma^2 = \Gamma dt \Rightarrow$ exactly cancels $\frac{\Gamma}{2} f''$ in (7)

$$\Rightarrow df(x(t)) = f'\left(x(t) + \frac{dx}{2}\right) dx \Leftrightarrow \frac{df}{dt} = f'(x) \dot{x} \quad (\text{strat})$$

so simple formula but complicated symmetrization

2.2) Generalization to $f(x(t), t)$

The derivation above generalizes directly to

$$\frac{df}{dt} f(x(t), t) = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} \dot{x}(t) + \frac{\Gamma}{2} \frac{\partial^2 f}{\partial x^2}$$

2.3) N-dimensional Itô formula

$\dot{x}_i = F_i(x_1, \dots, x_N) + \gamma_i$ when the $\{\gamma_i\}$ are correlated GWN s.t.

$$\langle \gamma_i(t) \rangle = 0 \quad \langle \gamma_i(t) \gamma_h(t') \rangle = \Gamma_{ih} \delta(t-t')$$

Then

$$\frac{df}{dt} f(x_1(t), \dots, x_N(t)) = \sum_i \frac{\partial f}{\partial x_i} \dot{x}_i + \frac{1}{2} \sum_{i,j,h} \frac{\partial^2 f}{\partial x_i \partial x_h} \Gamma_{ih} \quad (8)$$

Comment: Very useful in the presence of deterministic & stochastic variables.

$$\text{E.g. } \dot{x} = v \quad ; \quad m\ddot{v} = -\gamma v - v'(x) + \sqrt{2\sigma\mu\Gamma} \gamma(t)$$

$$\Leftrightarrow \dot{x} = v + \xi_x \quad ; \quad \dot{v} = -\frac{\gamma}{m} v - \frac{1}{m} v'(x) + \xi_y$$

when $\langle \xi_x(t) \rangle = 0$; $\langle \xi_x(t) \xi_x(t') \rangle = 0$

$$\langle \xi_y(t) \rangle = 0; \langle \xi_y(t) \xi_y(t') \rangle = \frac{2\delta kT}{m^2} \delta(t-t')$$

$$\langle \xi_x(t) \xi_y(t') \rangle = 0$$

$$\frac{d}{dt} f(x(t), v(t)) = \frac{\partial f}{\partial x} \dot{x} + \frac{\partial f}{\partial v} \dot{v} + \frac{mT}{m^2} \frac{\partial^2 f}{\partial v^2}$$

\Rightarrow only the stochastic variable leads to a second order derivative.

2.4] Back to the paradox

$$f(x(t)) = x^2(t) \quad \& \quad \dot{x}(t) = \sqrt{2D} \gamma(t)$$

$$f'(x) = 2x; \quad f''(x) = 2$$

$$\frac{d}{dt} f(x(t)) = \frac{\partial f}{\partial x} \cdot \dot{x} + \frac{1}{2} \cdot \frac{\partial^2 f}{\partial x^2} \cdot 2D = 2x \dot{x} + 2D = 2D + \sqrt{8D} x \gamma(t)$$

$$x^2(t) = 2Dt + \sqrt{8D} \int_0^t ds \gamma(s)$$

\rightarrow ① we recover $\langle x^2(t) \rangle = 2Dt$

② we can characterize the fluctuations of $x^2(t)$ around its mean $2Dt$.

Also works for higher moments:

$$\begin{aligned} \frac{d}{dt} \langle x^4(t) \rangle &= 4 \langle x^3 \dot{x} \rangle + \frac{1}{2} \cdot 2D \cdot 12 \langle x^2 \rangle \\ &= 4 \langle x^3 \rangle \underbrace{\langle \sqrt{2D} \gamma(t) \rangle}_{=0} + 12D \underbrace{\langle x^2 \rangle}_{2Dt} \end{aligned}$$

$$\Rightarrow \langle x^4(t) \rangle = 12D^2 t^2 = 3 \times (2Dt)^2 = 3 \langle x^2(t) \rangle^2 \text{ as expected for a GRV.}$$

3] Probability of noise realization

If we say that $\{\gamma(t)\}$ forms a set of GRV, it would be nice to be able to write their probability weight $P[\{\gamma(t)\}] = ?$

Start with N random variables \vec{z}_j such that $\vec{z} = (z_1, \dots, z_N)$ (4)

$$P(\vec{z}) = \frac{1}{Z} \exp \left[-\frac{1}{2} \vec{z} \cdot (\Gamma \vec{z}) \right] \quad (9)$$

with Γ a matrix symmetric positive definite.

From the psf you know that $\langle z_i z_j \rangle = k_{ij}$, with $K = \Gamma^{-1}$.

From $\langle z_i z_j \rangle = k_{ij}$, we can build $\Gamma = K^{-1}$ & $P(\vec{z})$. Can we do the same from $\langle \eta(t) \eta(t') \rangle$?

Now let's call $t_i = i dt$ and $\eta_i = \eta(t_i)$ and take the limit $dt \rightarrow 0$ keeping $N dt = t$ fixed. We then rewrite:

$$\vec{z} \cdot (\Gamma \vec{z}) = \sum_{i,j} z_i P_{ij} z_j = \sum_{i,j} dt^2 \eta(t_i) \frac{P_{ij}}{dt^2} \eta(t_j)$$

$$\vec{z} \cdot (\Gamma \vec{z}) \sim \int dt dt' \eta(t) \eta(t') P_c(t, t') \quad \text{where } P_c(t_i, t_j) = \frac{1}{dt^2} P_{ij} \quad (10)$$

① Can we build $K_c(t_i, t_j)$?

$$K = \Gamma^{-1} \Rightarrow \sum_h K_{ih} P_{hj} = \delta_{ij} \quad (11)$$

Take a function $f(t)$ & denote $f_i = f(t_i)$. Then (11) implies

$$\sum_{j,h} K_{ih} P_{hj} f_j = \sum_j \delta_{ij} f_j = f_i$$

$$\Leftrightarrow \sum_{j,h} dt^2 K_{ih} \frac{P_{hj}}{dt^2} f_j = f_i$$

$$\Leftrightarrow \int dt'' dt' K_c(t, t') P_c(t', t'') f(t'') = f(t) \quad \text{with } K_c(t_i, t_j) = k_{ij}$$

$$\Leftrightarrow \int dt'' f(t'') \left[\int dt' K_c(t, t') P_c(t', t'') \right] = f(t)$$

Since this holds for any function f , one has that

$$\Rightarrow \int dt' k_c(t, t') P_c(t', t'') = \delta(t - t'')$$

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This is the generalization of $K \cdot P = I_d$ for convolution kernel.

⑩ Going back to the GWN: $\langle \gamma(t) \gamma(t') \rangle = 2k_B T \delta(t - t') = k_c(t, t')$

\Rightarrow What is P_c ?

$$* \int dt f(t) \delta(t - t_j) \simeq f(t_j) = f_j = \sum_i f_i \delta_{ij} = \sum_i dt f_i \frac{\delta_{ij}}{dt} \Rightarrow \delta(t_i - t_j) \simeq \frac{\delta_{ij}}{dt}$$

$$* \langle \gamma(t_i) \gamma(t_j) \rangle = 2k_B T \frac{\delta_{ij}}{dt} \Rightarrow K_{ij} = 2k_B T \frac{\delta_{ij}}{dt}.$$

$$Eq (11) \text{ thus leads to } P_{j,h} = \frac{1}{2k_B T} dt \delta_{jh}$$

$$\text{Then, } Eq (10) \Rightarrow P_c(t_i, t_j) = \frac{1}{2k_B T} \frac{\delta_{jh}}{dt} \simeq \frac{\delta(t_i - t_j)}{2k_B T}$$

Indeed, we check that

$$\int dt k(t, t') P(t', t'') = \frac{2k_B T}{2k_B T} \int dt' \delta(t - t') \delta(t' - t'') = \delta(t - t'')$$

From there, we can build the noise probability distribution:

$$\Rightarrow P[\{\gamma(t)\}] = \frac{1}{Z} \exp \left[-\frac{1}{4k_B T} \int dt dt' \gamma(t) \gamma(t') \delta(t - t') \right]$$

$$P[\{\gamma(t)\}] = \frac{1}{Z} \exp \left[-\frac{1}{4k_B T} \int dt \gamma(t)^2 \right] \quad o-)$$

Colored noise If $\langle \gamma(t) \gamma(t') \rangle = K(t - t')$

$$\text{then } P[\{\gamma(t)\}] = \frac{1}{Z} \exp \left[- \int dt dt' \gamma(t) P(t - t') \gamma(t') \right]$$

$$\text{when } P \text{ is such that } \int dt' k(t - t') P(t' - t'') = \delta(t - t'')$$

4J Probability of trajectories $\{x(t)\}$

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If we know $P[\{x(t)\}]$ and we know $x(t, \{\gamma(s)\})$, can we get $P[\{x(t)\}]$? Yes, but this is painful...

Changing variables n rdm variables x_1, \dots, x_n & a new set of coordinates $y_i(x_1, \dots, x_n)$

Conservation of probability means that $P(x_1, \dots, x_n) dx_1 \dots dx_n = P(y_1, \dots, y_n) dy_1 \dots dy_n$
 $\Rightarrow P(y_1, \dots, y_n) = P(x_1, \dots, x_n) \cdot \underbrace{\left| \frac{dx_1 \dots dx_n}{dy_1 \dots dy_n} \right|}_{\text{Jacobian of the change of variable}}$

Here $P[\{x(t)\}] = P[\{\gamma(t)\}] \cdot \det \mathcal{J}$, where $\mathcal{J} = \left| \frac{\partial \gamma(t)}{\partial x(t)} \right|$

Q: How do we give a meaning to \mathcal{J} ?

Let's time-discretize the Lengyevim equation $\dot{x} = f(x) + \gamma(t)$

x_0 fixed, $x_i = x(t_i)$, $t_i = i \cdot \Delta t$. x_1, \dots, x_N are N RVs. Then, we define

$\tilde{x}_i = \int_{t_{i-1}}^{t_i} \gamma(s) ds$ so that \tilde{x}_i leads from x_{i-1} to x_i :

$x_{i+1} = x_i + \int_{t_i}^{t_{i+1}} f(x(s)) ds + \tilde{x}_{i+1} \Rightarrow \tilde{x}_1, \dots, \tilde{x}_N$ are N GRVs.

$$\Rightarrow \frac{\partial \tilde{x}_{i+1}}{\partial x_j} = \frac{\partial}{\partial x_j} \left[x_{i+1} - x_i - \underbrace{\int_{t_i}^{t_{i+1}} f(x(s)) ds}_{\text{easy}} \right]$$

$$=? = f(x_i) \Delta t ?$$

$$= f(x_{i+1}) \Delta t ?$$

$$= f(x_i^\alpha) \Delta t \text{ with } x_i^\alpha = x_i + \alpha(x_{i+1} - x_i) ?$$

All appear equivalent to order Δt ... Let's keep α arbitrary for now.

\Rightarrow the matrix $\frac{\partial \tilde{x}_{i+1}}{\partial x_i}$ is an upper triangular matrix

$$\begin{aligned}
 \Rightarrow \det &= \prod_i \frac{\partial \tilde{x}_i}{\partial x_i} = \prod_i (1 - \alpha \det f'(x_i^\alpha)) \underset{\alpha \rightarrow 0}{\approx} \prod_i e^{-\alpha \det f'(x_i^\alpha)} \quad (7) \\
 &\approx e^{-\alpha \sum_i \det f'(x_{i,ff}^\alpha)} \approx e^{-\alpha \int_0^T ds f'(x(s))} \\
 P[x(t)] &= \frac{1}{Z} e^{-\int dt \left[\frac{\gamma^2(t)}{4kT} + \alpha f'(x(s)) \right]}
 \end{aligned}$$

But we know that $\dot{x} = f(x) + \gamma(t) \Rightarrow \gamma(t) = \dot{x} - f(x)$

$$\Rightarrow P[x(t)] = \frac{1}{Z} e^{-\int dt \frac{(\dot{x} - f(x))^2}{4kT} + \alpha f'(x(s))} \quad \boxed{\text{Red Box}}$$

Comment: Causality makes us again choose $\alpha = 0$. Then

$$P[x(t)] = \frac{1}{Z} e^{-\int dt \frac{(\dot{x} - f(x))^2}{4kT}} \quad \boxed{\text{Red Box}}$$

Then, we need to use Itô calculus to compute time-derivatives in the integral.

If we use $\alpha = \frac{1}{2}$, we use what is called Stratonovich time discretization. We can use standard calculus in the exponent, but the computation of averages is harder since $\tilde{x}_{i,ff}$ and $x_{i,ff}$ are now correlated $\Rightarrow \langle x(t) \gamma(t) \rangle \neq 0$.

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